

MXD8666

SP6T Switch with MIPI for LTE Diversity



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General Description

The MXD8666 is a low loss, high isolation SP6T switch for antenna diversity receiving.

The MXD8666 is compatible with MIPI control, which is a key requirement for many cellular transceivers. This part is packaged in a compact 2mm x 2mm, 14-pin, QFN package which allows for a small solution size with no need for external DC blocking capacitors (when no external DC is applied to the device ports).

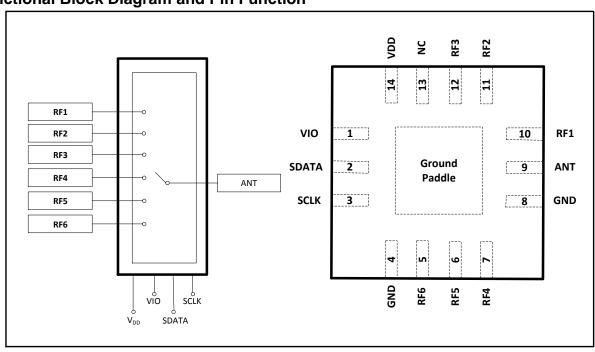
Features

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- Excellent insertion loss
 - 0.50 dB Insertion Loss at 2.7GHz
- P0.1dB @ 27dBm
- Multi-Band operation 700MHz to 3000MHz
- RFFE serial control interface
- Compact 2mm x 2mm in QFN-14 package
- No DC blocking capacitors required (unless external DC is applied to the RF ports)

Applications

- 2G/3G/4G antenna diversity
- Cellular modems and USB Devices



Functional Block Diagram and Pin Function

Figure 1 Functional Block Diagram and Pinout (Top View)

Application Circuit

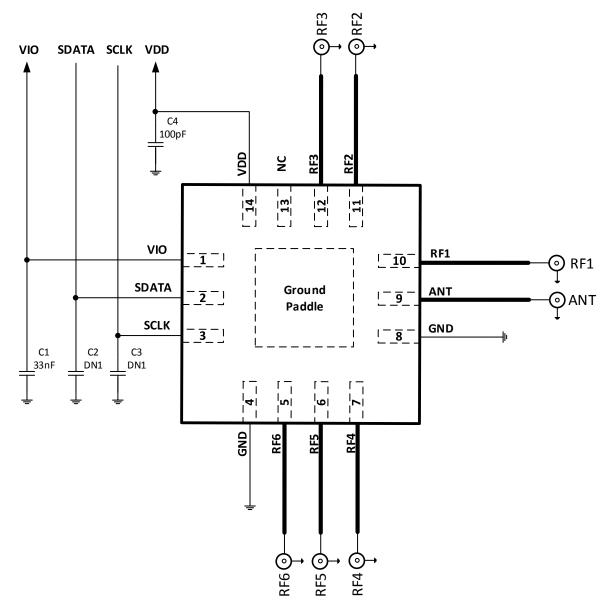


Figure 2 MXD8666 Evaluation Board Schematic

| Pin No. | Name | Description | Pin No. | Name | Description |
|------------------|-------|-------------------------|---------|------|--------------|
| 1 | VIO | Supply voltage for MIPI | 8 | GND | Ground |
| 2 | SDATA | MIPI data input/output | 9 | ANT | Antenna port |
| 3 | SCLK | MIPI clock | 10 | RF1 | RF port1 |
| 4 | GND | Ground | 11 | RF2 | RF port2 |
| 5 | RF6 | RF port6 | 12 | RF3 | RF port3 |
| 6 | RF5 | RF port5 | 13 | NC | NC |
| 7 | RF4 | RF port4 | 14 | VDD | Power supply |
| Ground Paddle | GND | Ground | | | |

Note: Bottom ground paddles must be connected to ground.

Truth Table

Table 2.

| Control | | | Switched RI | F Outputs | | |
|------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|
| Register_0 | RF1 | RF2 | RF3 | RF4 | RF5 | RF6 |
| 0x06 | Insertion Loss | Isolation | Isolation | Isolation | Isolation | Isolation |
| 0x04 | Isolation | Insertion Loss | Isolation | Isolation | Isolation | Isolation |
| 0x02 | Isolation | Isolation | Insertion Loss | Isolation | Isolation | Isolation |
| 0x05 | Isolation | Isolation | Isolation | Insertion Loss | Isolation | Isolation |
| 0x03 | Isolation | Isolation | Isolation | Isolation | Insertion Loss | Isolation |
| 0x01 | Isolation | Isolation | Isolation | Isolation | Isolation | Insertion Loss |
| 0x00 | Isolation | Isolation | Isolation | Isolation | Isolation | Isolation |

Recommended Operation Range

Table 3. Recommended Operation Condition

| Parameters | Symbol | Min | Тур | Max | Units |
|---------------------------|----------------|---------|-----|------|-------|
| Operation Frequency | f1 | 0.7 | - | 3.0 | GHz |
| Power supply | Vdd | 2.5 | 2.8 | 3.0 | V |
| Power supply for MIPI | Vio | 1.65 | 1.8 | 1.95 | V |
| MIPI Control Voltage High | V _H | 0.8*VIO | 1.8 | 1.95 | V |
| MIPI Control Voltage Low | VL | 0 | 0 | 0.3 | V |

Specifications

Table 4. Electrical Specifications

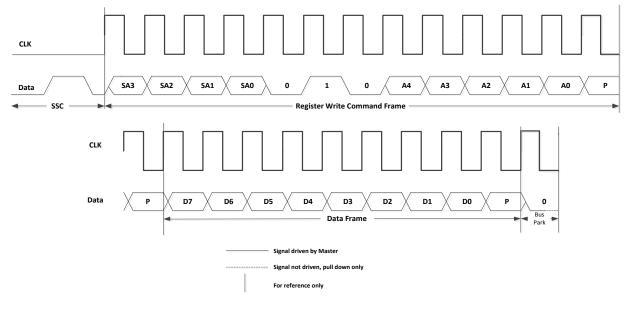
| Parameter | Symbol | Test Condition | Min | Typical | Max | Units |
|--|------------------|--|---------------------------|----------------------|-------------|----------------|
| DC Specifications | | | | • | | |
| Supply voltage | Vdd | | 2.5 | 2.8 | 3.0 | V |
| Supply current | ldd | | | 30 | 50 | uA |
| V _{IO} supply voltage | Vio | | 1.65 | 1.8 | 1.95 | V |
| V _{IO} Supply current | lio | | | 4 | 10 | uA |
| SDATA, SCLK control voltage: High Lo w | Vctl_h Vctl_l | | 0.8* V _{IO} 0 | V _{IO} 0 | 1.95 0.3 | V V |
| Switching Speed, one RF to another | | 10% to 90% RF | | 1 | 2 | uS |
| RF Specifications | | | - | | | |
| Insertion loss (ANT pin to RF1/2/3/4/5/6 pins) | IL | 0.1 to 1.0 GHz 1.0 to 2.0 GHz 2.0 to 2.7 GHz | | 0.30 0.40 0.50 | | dB dB dB |
| Isolation (ANT pin to RF1/2/3/4/5/6 pins) | lso | 0.1 to 1.0 GHz 1.0 to 2.0 GHz 2.0 to 2.7 GHz | 35 25 20 | 40 30 24 | | dB dB dB |
| Input return loss (ANT pin to RF1/2/3/4/5/6 pins) | RL | 0.1 to 1.0 GHz 1.0 to 2.0 GHz 2.0 to 2.7 GHz | 20 15 12 | 25 20 15 | | dB dB dB |
| 0.1 dB Compression Point (ANT pin to RF1/2/3/4/5/6 pins) | P0.1dB | 0.7 GHz to 3.0 GHz | | +27 | | dBm |

MIPI Read and Write Timing

MIPI supports the following Command Sequences:

- Register Write
- Register_0 Write
- Register Read

Figures 3 and 4 provide the timing diagrams for register write commands and read commands, respectively. Figure 5 shows the Register 0 Write Command Sequence. Refer to the MIPI Alliance Specification for RF Front-End Control Interface (RFFE), v1.10 (26 July 2011) for additional information on MIPI USID programming sequences and MIPI bus specifications.





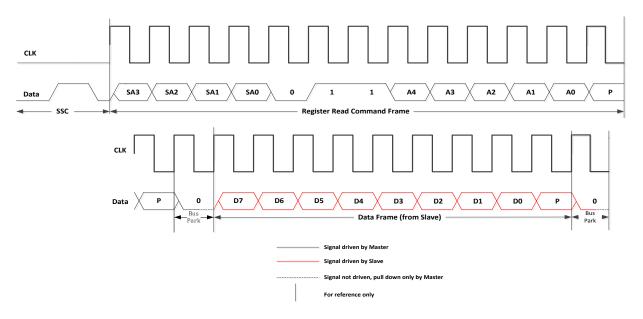


Figure 4 Register Read Command Sequence



In the timing figures, SA[3:0] is slave address. A[4:0] is register address. D[7:0] is data. "P" is odd parity bit.

Register 0 Write Command Sequence

Figure shows the Register 0 Write Command Sequence. The Command Sequence starts with an SSC, followed by the Register 0 Write Command Frame containing the Slave address, a logic one, and a seven bit word to be written to Register 0. The Command Sequence ends with a Bus Park Cycle.

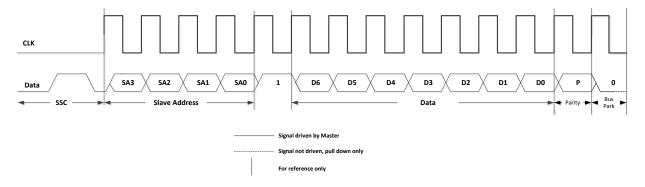


Figure 5 Register 0 Write Command Sequence

Register definition

Table 5. Register definition table

| Register Address | Register Name | Data Bits | R/W | Function | Description | Default | BROADC AST_ID support | Trigger support | |
|---------------------|---------------------|--------------|-----|----------------------------------|--|---|-----------------------------|--------------------|----|
| 0x00 | REGISTER_0 | 7:0 | R/W | RF Control | Register_0 truth Table: Table 2 | 0x00 | No | Yes | |
| | | | 7 | R/W | SOFTWARE RESET | 0: Normal operation 1: Software reset Note: On software reset, this register and all configurable registers are reset except for USID, GSID, and PM_TRIG. | 0 | No | No |
| | | 6 | R/W | COMMAND_FR AME_PARITY_E RR | Command Frame with parity error | 0 | No | No | |
| | | 5 | R/W | COMMAND_LE NGTH_ERR | Command Sequence with incorrect length | 0 | No | No | |
| 0x001A | RFFE_STATU S | 4 | R/W | ADDRESS_FRA ME_PARITY_E RR | Address Frame with parity error | 0 | No | No | |
| | | 3 | R/W | DATA_FRAME_ PARITY_ERR | Data Frame with parity error | 0 | No | No | |
| | | 2 | R/W | READ_UNUSED _REG | Read Command Sequence to an invalid address | 0 | No | No | |
| | | 1 | R/W | WRITE_UNUSE D_REG | Write Command Sequence to an invalid address | 0 | No | No | |
| | | 0 | R/W | BID_GID_ERR | Read Command Sequence with a BSID or GSID Note: Reading this register resets this register. | 0 | No | No | |
| 0004 D | | 7:4 | R | RESERVED | | 0x0 | No | No | |
| 0x001B | GROUP_SID | 3:0 | R/W | GSID | Group Slave ID | 0x0 | No | No | |
| | | 7:6 | R/W | PWR_MODE | 00: Normal Operation (ACTIVE) 01: Reset all registers to default settings (STARTUP) 10: Low power (LOW POWER) 11: Reserved Note: Write PWR_MODE=2'h1 will reset all register, and puts the device into STARTUP state. | 0b10 | Yes | No | |
| | | 5 | R/W | Trigger_Mask_2 | If this bit is set, trigger 2 is disabled | 0 | No | No | |
| | | 4 | R/W | Trigger_Mask_1 | If this bit is set, trigger 1 is disabled | 0 | No | No | |
| 0x001C PM_TRIG | PM_TRIG | 3 | R/W | Trigger_Mask_0 | If this bit is set, trigger 0 is disabled Note: When all triggers are disabled, writing to a register that is associated with trigger 0, 1, or 2, causes the data to go directly to the destination register. | 0 | No | No | |
| | | 2 | w | Trigger_2 | A write of a one to this bit loads trigger 2's registers | 0 | Yes | No | |
| | | 1 | W | Trigger_1 | A write of a one to this bit loads trigger 1's registers | 0 | Yes | No | |
| | | 0 | w | Trigger_0 | A write of a one to this bit loads trigger 0's registers Note: Trigger processed immediately then cleared. Trigger 0, 1, and 2 will always read as 0. | 0 | Yes | No | |
| 0x001D | PRODUCT_ID | 7:0 | R | PRODUCT_ID | Product Number | 0x5e | No | No | |
| 0x001E | MANUFACTU RER_ID | 7:0 | R | MANUFACTUR ER_ID[7:0] | Lower eight bits of MIPI registered Manufacturer ID | 0x81 | No | No | |
| | | 7:6 | R | RESERVED | | 0b00 | No | No | |
| 0x001F | MAN_USID | 5:4 | R | MANUFACTUR ER_ID[9:8] | Upper two bits of MIPI registered Manufacturer ID | 0b11 | No | No | |
| | | 3:0 | R/W | USID | USID of the device. | 0xb | No | No | |

Absolute Maximum Ratings

Table 6. Maximum ratings

| Parameters | Symbol | Minimum | Maximum | Units |
|--|------------------|---------|---------|-------|
| Supply voltage | V _{DD} | +2.0 | +3.3 | V |
| VIO Supply voltage | V _{IO} | +1.5 | +2.0 | |
| MIPI Control voltage (SDATA, SCLK) | V _{CTL} | 0 | +2.0 | V |
| RF input power (RF1 to RF6) | PIN | | +28 | dBm |
| Operating temperature | TOP | -20 | +85 | °C |
| Storage temperature | T _{STG} | -40 | +125 | °C |
| Electrostatic Discharge Human body model (HBM), Class 1C | ESD_HBM | | 1000 | |
| Machine Model (MM), Class A | ESD_MM | | 100 | V |
| Charged device model (CDM), Class III | ESD_CDM | | 500 | |

Note: Exposure to maximum rating conditions for extended periods may reduce device reliability. There is no damage to device with only one parameter set at the limit and all other parameters set at or below their nominal value. Exceeding any of the limits listed here may result in permanent damage to the device

Power ON and OFF sequence

Here is the recommendation about power-on/off sequence in order to avoid damaging the device.

Power ON

1) Apply voltage supply - VDD

2) Apply logic supply - V_{IO}

3) Wait 10µs or greater and then apply MIPI bus signals – SCLK and SDATA

4) Wait 5µs or greater after MIPI bus goes idle and then apply the RF Signal

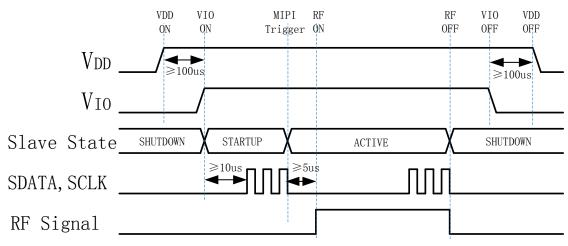
Power OFF

1) Remove the RF Signal

2) Remove MIPI bus - SCLK and SDATA

3) Remove logic supply - VIO

4) Remove voltage supply - VDD



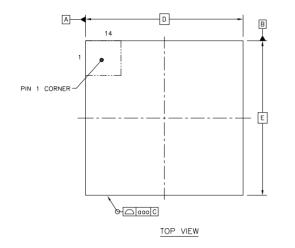
Note: VIO can be applied to the device before VDD or removed after VDD.

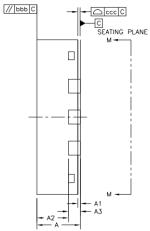
It is important to wait 10µs after VIO & VDD are applied before sending SDATA to ensure correction data transmission.

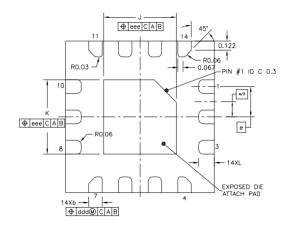
The minimum time between a power up and power down sequence (and vice versa) is \geq 100us.



Package Outline Dimension







| | 010100 | | MILLIMETER | | |
|--------------------|--------|-------|------------|-----------|------|
| DESCRIPTION | SYMBOL | MIN | NOM | MAX | |
| TOTAL THICKNESS | A | 0.50 | 0.55 | 0.60 | |
| STAND OFF | A1 | 0 | | 0.05 | |
| MOLD THICKNESS | | A2 | 0.35 | 0.40 | 0.45 |
| L/F THICKNESS | | A3 | | 0.152 REF | |
| LEAD WIDTH | b | 0.13 | 0.18 | 0.23 | |
| | х | D | 1.95 | 2.00 | 2.05 |
| BODY SIZE | Y | E | 1.95 | 2.00 | 2.05 |
| LEAD PITCH | | e | 0.40 BSC | | |
| EP SIZE | Х | J | 0.93 | 0.98 | 1.03 |
| LP SIZE | Y | к | 0.93 | 0.98 | 1.03 |
| LEAD LENGTH | | L | 0.16 | 0.21 | 0.26 |
| PACKAGE EDGE TOLEF | RANCE | 000 | 0.100 | | |
| MOLD FLATNESS | bbb | 0.100 | | | |
| COPLANARITY | | ccc | 0.080 | | |
| LEAD OFFSET | ddd | 0.100 | | | |
| EXPOSED PAD OFFSET | r | eee | 0.100 | | |

Figure 6 package outline dimension

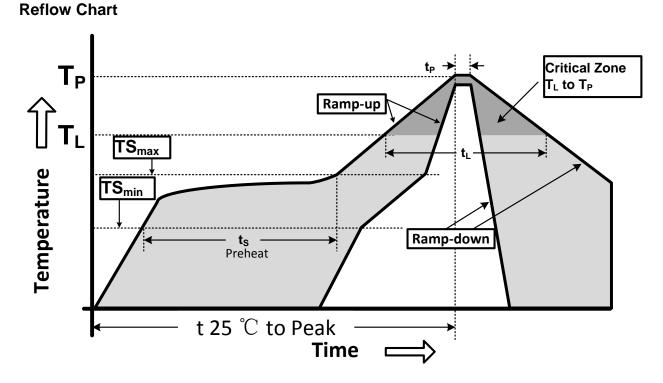


Figure 7 Recommended Lead-Free Reflow Profile

Table 7. Reflow condition

| Profile Parameter | Lead-Free Assembly, Convection, IR/Convection |
|---|---|
| Ramp-up rate $(TS_{max} to T_p)$ | 3°C/second max. |
| Preheat temperature (TS _{min} to TS _{max}) | 150℃ to 200℃ |
| Preheat time (t _s) | 60 - 180 seconds |
| Time above TL , 217 $^\circ\!\!\!{\rm C}$ (t_L) | 60 - 150 seconds |
| Peak temperature (T _p) | 260 °C |
| Time within 5 $^{\circ}$ C of peak temperature(t _p) | 20 - 40 seconds |
| Ramp-down rate | 6℃/second max. |
| Time 25°C to peak temperature | 8 minutes max. |

ESD Sensitivity

Integrated circuits are ESD sensitive and can be damaged by static electric charge. Proper ESD protection techniques should be used when handling these devices.

RoHS Compliant

This product does not contain lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyls (PBB) and polybrominated diphenyl ethers (PBDE), and are considered RoHS compliant.

1.1.1